* The heavier side of the robot needs to be closer to the drive station, otherwise it will fall over
* The front one goes all the way around (~180 deg) but the back side goes down and then back
* Watch the speeds – the back needed to have smaller gain than the front on the prototype
* Remember: the gearbox ratio needs to be LARGE
* Calculation to-do: will the arms extend too far out?
* Make sure the front arms can go around the back arms – remove the crossbar if necessary
* Can the arms support the weight of the robot?